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Mechatronics and Robotics Engineering for Advanced and Intelligent Manufacturing Springer Featuring selected contributions from the 2nd International Conference on Mechatronics and Robotics Engineering, held in Nice, France, February 18–19, 2016, this book introduces recent advances and state-of-the-art technologies in the field of advanced intelligent manufacturing. This systematic and carefully detailed collection provides a valuable reference source for mechanical engineering researchers who want to learn about the latest developments in advanced manufacturing and automation, readers from industry seeking potential solutions for their own applications, and those involved in the robotics and mechatronics industry. **Robotics and Automation Handbook CRC Press** As the capability and utility of robots has increased dramatically with new technology, robotic systems can perform tasks that are physically dangerous for humans, repetitive in nature, or require increased accuracy, precision, and sterile conditions to radically minimize human error. The Robotics and Automation Handbook addresses the major aspects of designing, fabricating, and enabling robotic systems and their various applications. It presents kinetic and dynamic methods for analyzing robotic systems, considering factors such as force and torque. From these analyses, the book develops several controls approaches, including servo actuation, hybrid control, and trajectory planning. Design aspects include determining specifications for a robot, determining its configuration, and utilizing sensors and actuators. The featured applications focus on how the specific difficulties are overcome in the development of the robotic system. With the ability to increase human safety and precision in applications ranging from handling hazardous materials and exploring extreme environments to manufacturing and medicine, the uses for robots are growing steadily. The Robotics and Automation Handbook provides a solid foundation for engineers and scientists interested in designing, fabricating, or utilizing robotic systems. **Machines, Mechanism and Robotics Proceedings of iNaCoMM 2017 Springer** This book offers a collection of original peer-reviewed contributions presented at the 3rd International and 18th National Conference on Machines and Mechanisms (iNaCoMM), organized by Division of Remote Handling & Robotics, Bhabha Atomic Research Centre, Mumbai, India, from December 13th to 15th, 2017 (iNaCoMM 2017). It reports on various theoretical and practical features of machines, mechanisms and robotics; the contributions include carefully selected, novel ideas on and approaches to design, analysis, prototype development, assessment and surveys. Applications in machine and mechanism engineering, serial and parallel manipulators, power reactor engineering, autonomous vehicles, engineering in medicine, image-based data analytics, compliant mechanisms, and safety mechanisms are covered. Further papers provide in-depth analyses of data preparation, isolation and brain segmentation for focused visualization and robot-based neurosurgery, new approaches to parallel mechanism-based Master-Slave manipulators, solutions to forward kinematic problems, and surveys and optimizations based on historical and contemporary compliant mechanism-based design. The spectrum of contributions on theory and practice reveals central trends and newer branches of research in connection with these topics. **Advances in Mechanical Engineering Select Proceedings of ICAME 2020 Springer Nature** This book presents select peer-reviewed proceedings of the International Conference on Advances in Mechanical Engineering (ICAME 2020). The contents cover latest research in several areas such as advanced energy sources, automation, mechatronics and robotics, automobiles, biomedical engineering, CAD/CAM, CFD, advanced engineering materials, mechanical design, heat and mass transfer, manufacturing and production processes, tribology and wear, surface engineering, ergonomics and human factors, artificial intelligence, and supply chain management. The book brings together advancements happening in the different domains of mechanical engineering, and hence, this will be useful for students and researchers working in mechanical engineering. **CAD/CAM, Robotics and Factories of the Future Proceedings of the 28th International Conference on CARs & FoF 2016 Springer** This volume is based on the proceedings of the 28th International Conference on CAD/CAM, Robotics and Factories of the Future. This book specially focuses on the positive changes made in the field of robotics, CAD/CAM and future outlook for emerging manufacturing units. Some of the important topics discussed in the conference are product development and sustainability, modeling and simulation, automation, robotics and handling systems, supply chain management and logistics, advanced manufacturing processes, human aspects in engineering activities, emerging scenarios in engineering education and training. The contents of this set of proceedings will prove useful to both researchers and practitioners. **Machines, Mechanism and Robotics Proceedings of iNaCoMM 2019 Springer Nature** This volume includes select papers presented during the 4th International and 19th National Conference on Machines and Mechanism (iNaCoMM 2019), held in Indian Institute of Technology, Mandi. It presents research on various aspects of design and analysis of machines and mechanisms by academic and industry researchers. **ROBOTICS MECHANICS AND CONTROL PHI Learning Pvt. Ltd.** This book focusses on one of the important classes of Robots known as manipulators or robotic arms, and provides a thorough treatment of its kinematics, dynamics, and control. The book also covers the problem of trajectory generation and robot programming. The text, apart from providing a detailed account of topics such as on taxonomy of robots, spatial description of rigid bodies, kinematics of manipulator, concept of dexterous workspace, concept of singularity, manipulator dynamics using both the Newton-Euler and Lagrangian approaches with a deeper insight into the manipulator dynamics, manipulator control, and programming, additionally encompasses topics on motion planning, intelligent control, and distributed control of manipulators. The book is an excellent learning resource for understanding the complexities of manipulator design, analysis, and operation. It clearly presents ideas without compromising on the mathematical rigour. **KEY FEATURES** • Full coverage of syllabi of all the Indian universities • Based on classroom-tested lecture notes • Numerous illustrative examples • Chapter-end problems for brainstorming Primarily designed for students studying Robotics in undergraduate and postgraduate engineering courses in mechanical and mechatronics disciplines, the book is also of immense value to the students pursuing research in robotics. Instructor Resources PPTs and Solution Manual are also available for the faculty members who adopt the book. **Introduction to Robotics Mechanics and Control Pearson Educación** Written for senior level or first year graduate level robotics courses, this text includes material from traditional mechanical engineering, control theoretical material and computer science. It includes coverage of rigid-body transformations and forward and inverse positional kinematics. **Advances in Motion Sensing and Control for Robotic Applications Selected Papers from the Symposium on Mechatronics, Robotics, and Control (SMRC'18)- CSME International Congress 2018, May 27-30, 2018 Toronto, Canada Springer** This book reports on advances in sensing, modeling and control methods for different robotic platforms such as multi-degree of freedom robotic arms, unmanned aerial vehicles and autonomous mobile platforms. Based on 2018 Symposium on Mechatronics, Robotics, and Control (SMRC'18), held as part of the 2018 CSME International Congress, in York University, Toronto, Canada, the book covers a variety of topics, from filtering and state estimation to adaptive control of reconfigurable robots and more. Next-generation systems with advanced control, planning, perception and interaction capabilities will achieve functionalities far beyond today's technology. Two key challenges remaining for advanced robot technologies are related to sensing and control in robotic systems. Advanced perception is needed to navigate changing environments. Adaptive and intelligent control systems must be developed to enable operation in unstructured and dynamic environments. The selected chapters in this book focus on both of the aforementioned areas and highlight the main trends and challenges in robot sensing and control. The first part of the book introduces chapters which focus on advanced perception and sensing for robotics applications. They include sensor filtering and state estimation for bipedal robots and motion capture systems analysis. The second part focuses on different modeling and control methods for robotic systems including flight control for UAVs, multi-variable robust control for modular and reconfigurable robotics and control for precision micromanipulation. **Introduction to Robotics, eBook, Global Edition Pearson Higher Ed** For senior-year undergraduate and first-year graduate courses in robotics. An intuitive introduction to robotic theory and application Since its original publication in 1986, Craig's Introduction to Robotics: Mechanics and Control has been the leading textbook for teaching robotics at the university level. Blending traditional mechanical engineering material with computer science and control theoretical concepts, the text covers a range of topics, including rigid-body transformations, forward and inverse positional kinematics, velocities and Jacobians of linkages, dynamics, linear and non-linear control, force control methodologies, mechanical design aspects, and robotic programming. The 4th Edition features a balance of application and theory, introducing the science and engineering of mechanical manipulation—establishing and building on foundational understanding of mechanics, control theory, and computer science. With an emphasis on the computational aspects of problems, the text aims to present material in a simple, intuitive manner. **Social Robotics 8th International Conference, ICSR 2016, Kansas City, MO, USA, November 1-3, 2016 Proceedings Springer** This book constitutes the refereed proceedings of the 8th International Conference on Social Robotics, ICSR 2016, held in Kansas City, MO, USA, in November 2016. The 98 revised full papers presented were carefully reviewed and selected from 107 submissions. The theme of the 2016 conference is Sociorobotics: Design and implementation of social behaviors of robots interacting with each other and humans. In addition to technical sessions, ICSR 2016 included three workshops: The Synthetic Method in Social Robotics (SMSR 2016), Social Robots: A Tool to Advance Interventions for Autism, and Using Social Robots to Improve the Quality of Life in the Elderly. **Modern Robotics Cambridge University Press** A modern and unified treatment of the mechanics, planning, and control of robots, suitable for a first course in robotics. **Advances in Industrial Machines and Mechanisms Select Proceedings of IPROMM 2020 Springer Nature** This book presents the select proceedings of the 1st International 13th National Conference on Industrial Problems on Machines and Mechanism (IPROMM 2020) and examines issues in the design, manufacture, and performance of mechanical and mechatronic elements and systems that are employed in modern machines and devices. The topics covered include robotics, industrial CAD/CAM systems, mechatronics, machinery associated with conventional and unconventional manufacturing systems, material handling and automated assembly, mechanical and electro-mechanical systems of modern machinery and equipment, micro-devices, compliant mechanisms, hybrid electric vehicle and electric vehicle mechanisms, acoustic and noise control. This book also discusses the recent advances in the integration of IoT and Industry 4.0 in mechanism and machines. The book will be a valuable reference for academicians, researchers, and professionals interested in the design and development of industrial machines. **Advances in Mechanical Engineering Selected Contributions from the Conference "Modern Engineering: Science and Education", Saint Petersburg, Russia, June 2020 Springer Nature** This book draws together the most interesting recent results to emerge in mechanical engineering in Russia, providing a fascinating overview of the state of the art in the field in that country which will be of interest to a wide readership. A broad range of topics and issues in modern engineering are discussed, including dynamics of machines, materials engineering, structural strength, transport technologies, machinery quality and innovations. The book comprises selected papers presented at the 9th conference "Modern Engineering: Science and Education", held at the Peter the Great Saint Petersburg Polytechnic University in June 2020 with the support of the Russian Engineering Union. The authors are experts in various fields of engineering, and all of the papers have been carefully reviewed. The book will be of interest to mechanical engineers, lecturers in engineering disciplines and engineering graduates. **Robot Analysis and Control John Wiley & Sons** Introduces the basic concepts of robot manipulation—the fundamental kinematic and dynamic analysis of manipulator arms, and the key techniques for trajectory control and compliant motion control. Material is supported with abundant examples adapted from successful industrial practice or advanced research topics. Includes carefully devised conceptual diagrams, discussion of current research topics with references to the latest publications, and end-of-book problem sets. Appendixes. Bibliography. **Advanced Computational Methods in Mechanical and Materials Engineering CRC Press** This book provides in-depth knowledge to solve engineering, geometrical, mathematical, and scientific problems with the help of advanced computational methods with a focus on mechanical and materials engineering. Divided into three subsections covering design and fluids, thermal engineering and materials engineering, each chapter includes exhaustive literature review along with thorough analysis and future research scope. Major topics covered pertain to computational fluid dynamics, mechanical performance, design, and fabrication including wide range of applications in industries as automotive, aviation, electronics, nuclear and so forth. Covers computational methods in design and fluid dynamics with a focus on computational fluid dynamics Explains advanced material applications and manufacturing in labs using novel alloys and introduces properties in material Discusses fabrication of graphene reinforced magnesium metal matrix for orthopedic applications Illustrates simulation and optimization gear transmission, heat sink and heat exchangers application Provides unique problem-solution approach including solutions, methodology, experimental setup, and results validation This book is aimed at researchers, graduate students in mechanical engineering, computer fluid dynamics, fluid mechanics, computer modeling, machine parts, and mechatronics. **Distinguished Figures in Mechanism and Machine Science: Their Contributions and Legacies Springer Science & Business Media** This

is the first part of a series of books whose aim is to collect contributed papers describing the work of famous persons in MMS (Mechanism and Machine Science). The current work treats mainly technical developments in the historical evolution of the fields that today are grouped in MMS. The emphasis is on biographical notes describing the efforts and experiences of people who have contributed to technical achievements. **Robot Mechanisms Springer Science & Business Media** This book provides a comprehensive introduction to the area of robot mechanisms, primarily considering industrial manipulators and humanoid arms. The book is intended for both teaching and self-study. Emphasis is given to the fundamentals of kinematic analysis and the design of robot mechanisms. The coverage of topics is untypical. The focus is on robot kinematics. The book creates a balance between theoretical and practical aspects in the development and application of robot mechanisms, and includes the latest achievements and trends in robot science and technology. **Control Problems in Robotics and Automation Springer** Focusing on the important control problems in state-of-the-art robotics and automation, this volume features invited papers from a workshop held at CDC, San Diego, California. As well as looking at current problems, it aims to identify and discuss challenging issues that are yet to be solved but which will be vital to future research directions. The many topics covered include: automatic control, distributed multi-agent control, multirobots, dexterous hands, flexible manipulators, walking robots, free-floating systems, nonholonomic robots, sensor fusion, fuzzy control, virtual reality, visual servoing, and task synchronization. Control Problems in Robotics and Automation will be of interest to all researchers, scientists and graduate students who wish to broaden their knowledge in robotics and automation and prepare themselves to address and resolve the control problems that will be faced in this field as we enter the twenty-first century. **Robotics I. K. International Pvt Ltd** Robotics is an applied engineering science that has been referred to as a combination of machine tool technology and computer science. It includes diverse fields such as machine design, control theory, microelectronics, computer programming, artificial intelligence, human factors and production theory. The present book provides a comprehensive introduction to robotics. The book covers a fair amount of kinematics and dynamics of the robots. It also covers the sensors and actuators used in robotics system. This book will be useful for mechanical, electrical, electronics and computer engineering students. Key Features Latest technological developments in robotics * Robotic classifications, robot programming, robotic sensors and actuators. * Kinematics and dynamic analysis of the Robot * Modular systems in robotics Advances in Robotics systems * Fuzzy logic control in Robotic systems * Biped robot * Bio-mimetic robot * Robot safety and layout * Robot calibration Numerical examples Relative merits and demerits of different robot systems About Author: Appu Kuttan KK is working as professor in Mechanical Engineering, NITK, Surathkal. He has worked as Head of the department during 2000-2004. Eleven Ph.D students have completed their degree under his guidance. He has contributed more than one hundred papers in international and national journals and conferences. He has 25 years of teaching and 22 years of research experience. His areas of interest are CAD/CAM, Robotics, Mechatronics, Finite element method, Smart materials and Control engineering **Recent Advances in Materials and Modern Manufacturing Select Proceedings of ICAMMM 2021 Springer Nature Digitizing Production Systems Selected Papers from ISPR2021, October 07-09, 2021 Online, Turkey Springer Nature** This book contains selected papers from International Symposium for Production Research 2021, held on October 7-9, 2021, online, Turkey. The book reports recent advances in production engineering and operations. It explores topics including production research; production management; operations management; industry 4.0; industrial engineering; mechanical engineering; engineering management; and operational research. Presenting real-life applications, case studies, and mathematical models, this book is of interest to researchers, academics, and practitioners in the field of production and operation engineering. It provides both the results of recent research and practical solutions to real-world problems. **Fundamentals of Robotic Mechanical Systems Theory, Methods, and Algorithms Springer** Modern robotics dates from the late 1960s, when progress in the development of microprocessors made possible the computer control of a multiaxial manipulator. Since then, robotics has evolved to connect with many branches of science and engineering, and to encompass such diverse fields as computer vision, artificial intelligence, and speech recognition. This book deals with robots - such as remote manipulators, multifingered hands, walking machines, flight simulators, and machine tools - that rely on mechanical systems to perform their tasks. It aims to establish the foundations on which the design, control and implementation of the underlying mechanical systems are based. The treatment assumes familiarity with some calculus, linear algebra, and elementary mechanics; however, the elements of rigid-body mechanics and of linear transformations are reviewed in the first chapters, making the presentation self-contained. An extensive set of exercises is included. Topics covered include: kinematics and dynamics of serial manipulators with decoupled architectures; trajectory planning; determination of the angular velocity and angular acceleration of a rigid body from point data; inverse and direct kinematics manipulators; dynamics of general parallel manipulators of the platform type; and the kinematics and dynamics of rolling robots. Since the publication of the previous edition there have been numerous advances in both the applications of robotics (including in laparoscopy, haptics, manufacturing, and most notably space exploration) as well as in the theoretical aspects (for example, the proof that Hurst's 40th-degree polynomial is indeed minimal - mentioned as an open question in the previous edition). **Advances in Materials Research Select Proceedings of ICAMR 2019 Springer Nature** This book comprises select peer-reviewed proceedings of the International Conference on Advances in Materials Research (ICAMR 2019). The contents cover latest research in materials and their applications relevant to composites, metals, alloys, polymers, energy and phase change. The indigenous properties of materials including mechanical, electrical, thermal, optical, chemical and biological functions are discussed. The book also elaborates the properties and performance enhancement and/or deterioration in order of the modifications in atomic particles and structure. This book will be useful for both students and professionals interested in the development and applications of advanced materials. **Robot Analysis The Mechanics of Serial and Parallel Manipulators John Wiley & Sons** Complete, state-of-the-art coverage of robot analysis This unique book provides the fundamental knowledge needed for understanding the mechanics of both serial and parallel manipulators. Presenting fresh and authoritative material on parallel manipulators that is not available in any other resource, it offers an in-depth treatment of position analysis, Jacobian analysis, statics and stiffness analysis, and dynamical analysis of both types of manipulators, including a discussion of industrial and research applications. It also features: * The homotopy continuation method and dialytic elimination method for solving polynomial systems that apply to robot kinematics * Numerous worked examples and problems to reinforce learning * An extensive bibliography offering many resources for more advanced study Drawing on Dr. Lung-Wen Tsai's vast experience in the field as well as recent research publications, Robot Analysis is a first-rate text for upper-level undergraduate and graduate students in mechanical engineering, electrical engineering, and computer studies, as well as an excellent desktop reference for robotics researchers working in industry or in government. **Advances in Mechanical Engineering Select Proceedings of CAMSE 2020 Springer Nature** This book presents the select proceedings of Congress on Advances in Materials Science and Engineering (CAMSE 2020). It focuses on the state-of-the-art research, development, and commercial prospective of recent advances in mechanical engineering. The book covers various synthesis and fabrication routes of functional and smart materials for applications in mechanical engineering, manufacturing, physics, chemical and biological sciences, metrology, optimization and artificial intelligence among others. This book will be a useful resource for researchers, academicians as well as professionals interested in the highly interdisciplinary field of materials science and mechanical engineering. **Optimization of the Mechanical Engineering, Manufacturing Systems, Robotics and Aerospace Trans Tech Publications Ltd** Volume is indexed by Thomson Reuters CPCI-S (WoS). The main objective of this volume is to present the current understanding of leading researchers, engineers and scientists - from Romania and from around the world - concerning these fields in order to provide a platform from where researchers, engineers, academicians as well as industrial professionals can present their latest experiences and developmental activities in the mechanical engineering, manufacturing systems, robotics, medical and military fields. **Industrial Robots Programming Building Applications for the Factories of the Future Springer Science & Business Media** Industrial Robots Programming focuses on designing and building robotic manufacturing cells, and explores the capabilities of today's industrial equipment as well as the latest computer and software technologies. Special attention is given to the input devices and systems that create efficient human-machine interfaces, and how they help non-technical personnel perform necessary programming, control, and supervision tasks. Drawing upon years of practical experience and using numerous examples and illustrative applications, J. Norberto Pires covers robotics programming as it applies to: The current industrial robotic equipment including manipulators, control systems, and programming environments. Software interfaces that can be used to develop distributed industrial manufacturing cells and techniques which can be used to build interfaces between robots and computers. Real-world applications with examples designed and implemented recently in the lab. Industrial Robots Programming has been selected for indexing by Scopus. For more information about Industrial Robotics, please find the author's Industrial Robotics collection at the iTunesU University of Coimbra channel. **Proceedings of the First Symposium on Aviation Maintenance and Management-Volume II Springer Science & Business Media** Proceedings of the First Symposium on Aviation Maintenance and Management collects selected papers from the conference of ISAMM 2013 in China held in Xi'an on November 25-28, 2013. The book presents state-of-the-art studies on the aviation maintenance, test, fault diagnosis, and prognosis for the aircraft electronic and electrical systems. The selected works can help promote the development of the maintenance and test technology for the aircraft complex systems. Researchers and engineers in the fields of electrical engineering and aerospace engineering can benefit from the book. Jinsong Wang is a professor at School of Mechanical and Electronic Engineering of Northwestern Polytechnical University, China. **Proceedings of the 7th International Conference on Industrial Engineering (ICIE 2021) Volume I Springer Nature** This book highlights recent findings in industrial, manufacturing and mechanical engineering, and provides an overview of the state of the art in these fields, mainly in Russia and Eastern Europe. A broad range of topics and issues in modern engineering is discussed, including the dynamics of machines and working processes, friction, wear and lubrication in machines, surface transport and technological machines, manufacturing engineering of industrial facilities, materials engineering, metallurgy, control systems and their industrial applications, industrial mechatronics, automation and robotics. The book gathers selected papers presented at the 7th International Conference on Industrial Engineering (ICIE), held in Sochi, Russia, in May 2021. The authors are experts in various fields of engineering, and all papers have been carefully reviewed. Given its scope, the book will be of interest to a wide readership, including mechanical and production engineers, lecturers in engineering disciplines, and engineering graduates. **Practical and Experimental Robotics CRC Press** Taking a completely hands-on approach, using cheap and easily available robotics kits, Practical and Experimental Robotics provides a detailed exploration of the construction, theory, and experiments for different types of robots. With topics ranging from basic stamp microcontrollers to biped and propeller based robots, the text contains laboratory experiments, examples with solutions, and case studies. The authors begin with a review of the essential elements of electronics and mechanics. They describe the basic mechanical construction and electrical control of the robot, then give at least one example of how to operate the robot using microcontrollers or software. The book includes a reference chapter on Basic Stamp Microcontrollers with example code pieces and a chapter completely devoted to PC interfacing. Each chapter begins with the fundamentals, then moves on to advanced topics, thus building a foundation for learning from the ground up. Building a bridge between technicians who have hands-on experience and engineers with a deeper insight into the workings, the book covers a range of machines, from arm, wheel, and leg robots to flying robots and robotic submarines and boats. Unlike most books in this field, this one offers a complete set of topics from electronics, mechanics, and computer interface and programming, making it an independent source for knowledge and understanding of robotics. **Finite and Instantaneous Screw Theory in Robotic Mechanism Springer Nature** This book presents a finite and instantaneous screw theory for the development of robotic mechanisms. It addresses the analytical description and algebraic computation of finite motion, resulting in a generalized type synthesis approach. It then discusses the direct connection between topology and performance models, leading to an integrated performance analysis and design framework. The book then explores parameter uncertainty and multiple performance requirements for reliable, optimal design methods, and describes the error accumulation principle and parameter identification algorithm, to increase robot accuracy. It proposes a unified and generic methodology, and applies to the invention, analysis, design, and calibration of robotic mechanisms. The book is intended for researchers, graduate students and engineers in the fields of robotic mechanism and robot design and applications. **Rapid Damage-Free Robotic Harvesting of Tomatoes Springer Nature** This book shares the latest findings on this topic, systematically introduces readers to advances made in robotic harvesting around the globe, and explores the relations between the development of robotic harvesting and the respective social/economic conditions and agricultural business patterns in various countries/regions. Due to the unstructured setting it is used in, and to the significant differences between individual fruit and vegetable targets, robotic harvesting is currently considered to be one of the most challenging robotics technologies. Accordingly, research into this area involves the integration of various aspects, including biomechanics, optimization design, advanced perception and intelligent control. In addition to rapid and damage-free robotic harvesting, which reflects the multidisciplinary nature of the topic, further aspects addressed include gripping collisions with viscoelastic objects, using lasers to cut plant material, plant-fruit response to vacuum sucking and pulling, and performance probability distribution. Highlighting outstanding innovations and reflecting the latest advances in intelligent agricultural equipment in China, the book offers a unique and valuable resource. **Handbook of Research on Green Engineering Techniques for Modern Manufacturing IGI Global** Green manufacturing has developed into an essential aspect of contemporary manufacturing practices, calling for environmentally friendly and sustainable techniques. Implementing successful green manufacturing processes not only improves business efficiency and competitiveness but also reduces harmful production in the environment. The Handbook of Research on Green Engineering Techniques for Modern Manufacturing provides emerging perspectives on the theoretical and practical aspects of green industrial concepts, such as green supply chain management and reverse logistics, for the sustainable utilization of resources and applications within manufacturing and engineering. Featuring coverage on a broad range of topics such as additive manufacturing, integrated manufacturing systems, and machine materials, this publication is ideally designed for engineers, environmental professionals, researchers, academicians, managers, policymakers, and graduate-level students seeking current research on recent and sustainable practices in manufacturing processes. **Proceedings of 10th International Conference on Mechatronics and Control Engineering ICMCE 2021 Springer Nature** This volume consists

of selected peer reviewed papers from the 10th International Conference on Mechatronics and Control Engineering (ICMCE 2021) discussing latest advances in mechanical engineering and dynamic analysis, sensor technology and application, mechanical design and system modelling, control system and engineering, robot design and control engineering, development and performance analysis of functional materials. Additional themes include methodologies, algorithms, applications and knowledge discovery in mechatronics and control engineering. This volume will prove a valuable resource for those in academia and industry. **Advanced Manufacturing Systems and Innovative Product Design Select Proceedings of IPDIMS 2020 Springer Nature** This book comprises select papers presented at the Conference on Innovative Product Design and Intelligent Manufacturing System (IPDIMS 2020). The book discusses the latest methods and advanced tools from different areas of design and manufacturing technology. The main topics covered include design methodologies, industry 4.0, smart manufacturing, and advances in robotics among others. The contents of this book are useful for academics as well as professionals working in the areas of industrial design, mechatronics, robotics, and automation. **Human-Friendly Robotics 2019 12th International Workshop Springer Nature** This book covers a wide range of topics related to human-robot interaction, both physical and cognitive, including theories, methodologies, technologies, and empirical and experimental studies. The International Workshop on Human-Friendly Robotics (HFR) is an annual meeting that brings together academic scientists, researchers and research scholars to present their latest, original findings on all aspects concerning the introduction of robots into everyday life. The growing need to automate daily tasks, combined with new robot technologies, is driving the development of human-friendly robots, i.e., safe and dependable machines that operate in close proximity to humans or directly interact with them in a wide range of contexts. The technological shift from classical industrial robots, which are safely kept away from humans in cages, to robots that are used in close collaboration with humans, is faced with major challenges that need to be overcome. The objective of the workshop was to stimulate discussion and exchange knowledge on design, control, safety and ethical issues concerning the introduction of robots into everyday life. The 12th installment was organized by the University of Modena and Reggio Emilia and took place in Reggio Emilia, Italy. **Proceedings of the 7th International Conference on Industrial Engineering (ICIE 2021) Volume II Springer Nature** This book highlights recent findings in industrial, manufacturing and mechanical engineering, and provides an overview of the state of the art in these fields, mainly in Russia and Eastern Europe. A broad range of topics and issues in modern engineering is discussed, including the dynamics of machines and working processes, friction, wear and lubrication in machines, surface transport and technological machines, manufacturing engineering of industrial facilities, materials engineering, metallurgy, control systems and their industrial applications, industrial mechatronics, automation and robotics. The book gathers selected papers presented at the 7th International Conference on Industrial Engineering (ICIE), held in Sochi, Russia, in May 2021. The authors are experts in various fields of engineering, and all papers have been carefully reviewed. Given its scope, the book will be of interest to a wide readership, including mechanical and production engineers, lecturers in engineering disciplines, and engineering graduates. **Proceedings of 15th International Conference on Electromechanics and Robotics "Zavalishin's Readings" ER(ZR) 2020, Ufa, Russia, 15-18 April 2020 Springer Nature** This book features selected papers presented at the 15th International Conference on Electromechanics and Robotics "Zavalishin's Readings" - ER(ZR) 2020, held in Ufa, Russia, on 15-18 April 2020. The contributions, written by professionals, researchers and students, cover topics in the field of automatic control systems, electromechanics, electric power engineering and electrical engineering, mechatronics, robotics, automation and vibration technologies. The Zavalishin's Readings conference was established as a tribute to the memory of Dmitry Aleksandrovich Zavalishin (1900-1968) - a Russian scientist, corresponding member of the USSR Academy of Sciences and founder of the school of valve energy converters based on electric machines and valve converters energy. The first conference was organized by the Institute of Innovative Technologies in Electromechanics and Robotics at the Saint Petersburg State University of Aerospace Instrumentation in 2006. **Recent Trends in Mechanical Engineering Select Proceedings of ICOFTIME 2020 Springer Nature** This book presents the select peer-reviewed proceedings of the International Conference on Futuristic Trends in Mechanical Engineering (ICOFTIME 2020). The contents focus on latest research in different areas of mechanical engineering such as additive manufacturing, vibrations, robotics and automation, nano and smart materials, green energy, supply chain management, aviation, and biomechanics. The book also includes numerical and optimization methods relevant for several real-life mechanical engineering problems. Given its contents, this book will prove useful for researchers and professionals alike.